

Slope Stability MTT6201 - MEKANIKA TANAH

12st session 1.5 hours

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SEMESTER SYLLABUS

SYLLABUS

- 1. Introduction
- 2. Pengertian Tentang Tanah dan Batuan, Partikel Tanah
- 3. Analisis Ayakan dan Analysis Hydrometer
- 4. Hubungan Volume, Berat, Porositas, Kadar air, Kerapatan Relative Tanah
- 5. Konsistensi Tanah, Batas Plastis, Batas Cair
- 6. Klasifikasi tanah berdasarkan USDA, AASHTO, dan Unified
- 7. Tegangan Efektif dan penentuan tegangan bidang

Mid Term

OBJECTIVE

- 1. Konsep Tegangan, regangan, dan kekuatan tanah
- 2. Kekuatan geser tanah
- 3. Kompaksi
- 4. Permeabilitas dan rembesan
- 5. Aliran Air dalam tanah
- 6. Kestabilan lereng
- 7. Daya dukung tanah
- **Final Term**

Hubungan Volume dan berat

Stresses in Soil





Hubungan Volume dan berat

Shear Strength in Soil



Failure in Surface

Shear Strength in Soil







Types



Cruden and Varnes (1996) classied the slope failures into the following ve major categories. They are

- 1. Fall. This is the detachment of soil and/or rock fragments that fall down a slope
- 2. Topple. This is a forward rotation of soil and/or rock mass about an axis below the center of gravity of mass being displaced
- **3. Slide.** This is the downward movement of a soil mass occurring on a surface of rupture
- 4. Spread. This is a form of slide by translation. It occurs by "sudden movement of water-bearing seams of sands or silts overlain by clays or loaded by silts".
- 5. Flow. This is a downward movement of soil mass similar to a viscous fluid



When F_s is equal to 1, the slope is in a state of impending failure. Generally, a value of 1.5 for the factor of safety with respect to strength is acceptable for the design of a stable slope.

Simple case – Infinite Slope



 $W = (Volume of soil element) \times (Unit weight of soil) = \gamma LH$

$$\sigma' = \frac{N_a}{\text{Area of base}} = \frac{\gamma L H \cos \beta}{\left(\frac{L}{\cos \beta}\right)} = \gamma H \cos^2 \beta$$
$$\tau = \frac{T_a}{\text{Area of base}} = \frac{\gamma L H \sin \beta}{\left(\frac{L}{\cos \beta}\right)} = \gamma H \cos \beta \sin \beta$$

Without Seepage

$$F_s = \frac{c'}{\gamma H \, \cos^2 \beta \, \tan \beta} + \frac{\tan \phi'}{\tan \beta}$$

With Seepage

$$F_{s} = \frac{c'}{\gamma_{sat}H\cos^{2}\beta\,\tan\beta} + \frac{\gamma'\,\tan\phi'}{\gamma_{sat}\,\tan\beta}$$

Slope failure – Finite Slope

Plane - Culmann



$$W_a = \text{normal component} = W \cos \theta = \frac{1}{2} \gamma H^2 \left[\frac{\sin(\beta - \theta)}{\sin \beta \sin \theta} \right] \cos \theta$$

$$T_a = \text{tangential component} = W \sin \theta = \frac{1}{2} \gamma H^2 \left[\frac{\sin(\beta - \theta)}{\sin \beta \sin \theta} \right] \sin \theta$$

$$\tau' = \frac{N_a}{(\overline{AC})(1)} = \frac{N_a}{\left(\frac{H}{\sin\theta}\right)} \qquad \tau = \frac{T_a}{(\overline{AC})(1)} = \frac{T_a}{\left(\frac{H}{\sin\theta}\right)}$$
$$= \frac{1}{2}\gamma H \left[\frac{\sin(\beta - \theta)}{\sin\beta\,\sin\theta}\right] \cos\theta\,\sin\theta \qquad = \frac{1}{2}\gamma H \left[\frac{\sin(\beta - \theta)}{\sin\beta\,\sin\theta}\right] \sin^2\theta$$

$$c'_{d} = \frac{\gamma H}{4} \left[\frac{1 - \cos(\beta - \phi'_{d})}{\sin \beta \, \cos \phi'_{d}} \right]$$

The maximum height of the slope for which critical equilibrium occurs

$$H_{\rm cr} = \frac{4c'}{\gamma} \left[\frac{\sin\beta \,\cos\phi'}{1 - \cos(\beta - \phi')} \right]$$

Culmann's analysis is based on the assumption that the failure of a slope occurs along a plane when the average shearing stress tending to cause the slip is more than the shear strength of the soil. Also, the most critical plane is the one that has a minimum ratio of the average shearing stress that tends to cause failure to the shear strength of soil.

Slope failure – Finite Slope

Circular – Failure Modes



In general, nite slope failure occurs in one of the following modes :

- 1. When the failure occurs in such a way that the surface of sliding intersects th slope at or above its toe, it is called a **slope failure**
 - The failure circle is referred to as a **toe circle** if it passes through the toe of the slope,
 - And as a slope circle if it passes above the toe of the slope. Under certain circumstances, a shallow slope failure can occur,
- When the failure occurs in such a way that the surface of sliding passes at some distance below the toe of the slope, it is called a base failure The failure circle in the case of base failure is called a midpoint circle.

Slope failure – Finite Slope

Circular – Types of Analysis



- 1. Mass procedure: In this case, the mass of the soil above the surface of sliding is taken as a unit. This procedure is useful when the soil that forms the slope is assumed to be homogeneous, although this is not the case in most natural slopes.
- 2. Method of slices: In this procedure, the soil above the surface of sliding is divided into a number of vertical parallel slices. The stability of each slice is calculated separately. This is a versatile technique in which the nonhomogeneity of the soils and pore water pressure can be taken into consideration. It also accounts for the variation of the normal stress along the potential failure surface.

Analysis – Mass Procedure



Michalowski's analysis for stability of simple slopes

Types of analysis :

- Mass Procedure—Slopes in Homogeneous Clay Soil with φ=0
- Slopes in Clay Soil with φ = 0; and c_u Increasing with Depth
- Mass Procedure—Slopes in Homogeneous c' φ' Soil (Analysis of Michalowski (2002))



Contours of equal factors of safety:

- (a) slope 1 vertical to 0.5 horizontal;
- (b) slope 1 vertical to 0.75 horizontal

Analysis – Slice Methods



Types of analysis :

- Ordinary Methods of Slices
- Bishop's Simplified Method of Slices
- Bishop and Morgenstern solution
- Spencer's solution
- Michalowski's solution

Slice Methods – Ordinary Methods of Slices



Slice Methods – Bishop's Simplified Method of Slices



In 1955, Bishop proposed a more rened solution to the ordinary method of slices.

In this method, **the effect of forces on the sides of each slice** are accounted for to some degree

	005 m 1	$\tan \phi' \sin \alpha_n$	
$m_{\alpha(n)} =$	$\cos \alpha_n +$	F _s	



Slice Methods – Bishop and Morgenstern solution

In this method, **the effect of forces on the sides of each slice** are accounted for to some degree

$$r_{u(n)} = \frac{u_n}{\gamma z_n} = \frac{h_n \gamma_w}{\gamma z_n}$$

$$F_{s} = \left[\frac{1}{\sum_{n=1}^{n=p} \frac{b_{n} z_{n}}{H H} \sin \alpha_{n}}\right] \times \sum_{n=1}^{n=p} \left\{\frac{\left\lfloor\frac{c'}{\gamma H} \frac{b_{n}}{H} + \frac{b_{n} z_{n}}{H H} (1-r_{u}) \tan \phi'\right\rfloor}{m_{\alpha(n)}}\right\}$$

$$F_s = m' - n'r_u$$

Step 1. Obtain ϕ', β , and $c'/\gamma H$.

- **Step 2.** Obtain r_u (weighted average value).
- **Step 3.** From Table 15.5, obtain the values of m' and n' for D = 1, 1.25, and 1.5 (for the required parameters ϕ', β, r_w , and $c'/\gamma H$).

Step 4. Determine F_{n} , using the values of m' and n' for each value of D.

Step 5. The required value of F_s is the smallest one obtained in Step 4.

a. Stability coefficients m' and n' for $c'/\gamma H = 0$

			Stabili	ty coefficie	nts for eart	h slopes		
	Slope 2:1		Slope 3:1		Slope 4:1		Slope 5:1	
φ'	m'	n'	m'	n'	m'	n'	m'	n'
10.0	0.353	0.441	0.529	0.588	0.705	0.749	0.882	0.917
12.5	0.443	0.554	0.665	0.739	0.887	0.943	1.109	1.153
15.0	0.536	0.670	0.804	0.893	1.072	1.139	1.340	1.393
17.5	0.631	0.789	0.946	1.051	1.261	1.340	1.577	1.639
20.0	0.728	0.910	1.092	1.213	1.456	1.547	1.820	1.892
22.5	0.828	1.035	1.243	1.381	1.657	1.761	2.071	2.153
25.0	0.933	1.166	1.399	1.554	1.865	1.982	2.332	2.424
27.5	1.041	1.301	1.562	1.736	2.082	2.213	2.603	2.706
30.0	1.155	1.444	1.732	1.924	2.309	2.454	2.887	3.001
32.5	1.274	1.593	1.911	2.123	2.548	2.708	3.185	3.311
35.0	1.400	1.750	2,101	2.334	2.801	2.977	3.501	3.639
37.5	1.535	1.919	2.302	2.558	3.069	3.261	3.837	3.989
40.0	1.678	2.098	2.517	2.797	3.356	3.566	4.196	4.362

Slice Methods – Spencer's solution

Bishop's simplied method of slices described satisfies the equations of equilibrium with **respect to the moment but not with respect to the forces**

Spencer (1967) has provided a method to determine the factor of safety (F $_{\rm s})$ by taking into account the interslice forces



Step 1. Determine $c', \gamma, H, \beta, \phi'$, and r_u for the given slope. **Step 2.** Assume a value of F_s . **Step 3.** Calculate $c'/[F_{s(assumed)} \gamma H]$. \uparrow **Step 2**

Step 4. With the value of $c'/F_s\gamma H$ calculated in step 3 and the slope angle β , enter the proper chart in Figure 15.35 to obtain ϕ'_d . Note that Figures 15.35 a, b, and c, are, respectively, for r_u of 0, 0.25, and 0.5, respectively.

Step 5. Calculate
$$F_s = \tan \phi' / \tan \phi'_d$$
.

Step 4

Step 6. If the values of *F*₃ as assumed in step 2 are not the same as those calculated in step 5, repeat steps 2, 3, 4, and 5 until they are the same.

Slice Methods – Spencer's solution (Location Failure Circle)

Bishop's simplied method of slices described satisfies the equations of equilibrium with **respect to the moment but not with respect to the forces**

Spencer (1967) has provided a method to determine the factor of safety (F $_{\rm s})$ by taking into account the interslice forces





Michalowski (2002) used the kinematic approach to

Slice Methods – Michalowski's solution

c'			tan	φ'			
$\gamma H \tan \phi'$	$\beta = 15^{\circ}$	$\beta = 30^{\circ}$	$\beta = 45^{\circ}$	$\beta = 60^{\circ}$	$\beta = 75^{\circ}$	$\beta = 90^{\circ}$	
0	3.09	1.21	0.82	0.21			
0.05	3.83	1.96	1.27	0.75	0.29		
0.1	4.38	2.43	1.66	1.14	0.68		
0.2	5.10	3.30	2.37	1.81	1.31	0.70	
0.3	6.05	4.09	3.05	2.43	1.86	1.29	
0.4	6.84	4.79	3.71	3.00	2.39	1.75	
0.5	7.74	5.42	4.35	3.58	2.88	2.21	
1.0	11.70	8.81	7.41	6.23	5.21	4.22	
1.5		12.17	10.44	8.91	7.55	6.15	
2.0			13.42	11.59	9.81	8.10	
2.5				14.24	12.16	10.08	
3.0						11.95	



Tools



Tools



Tools



Tools



Source : Braja M Das, 2015;

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Tools

